Machine Learning Classification 1 and 2

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Topics - you should be able to explain

- Data and data preprocessing
- Features and labels
- Statistical classification
- Bayes decision rule for classification
- Generative classifier vs discriminative classifier
- Curse of dimensionality
- Naive Bayes model
- Multivariate Gaussian distributions
- Gaussian discriminant analysis (GDA)
- Covariance matrices
- Decision regions and decision boundaries
- Minimum error rate classification, MAP decision rule
- Discriminant functions of GDA
- Linear discriminant analysis (LDA)

Topics - you should be able to explain (cont.)

- Linear classifiers
- Hyperplanes, decision boundaries, and decision regions
- Training of classifiers
- Loss and cost functions
- Logistic regression
- Extension of binary classification to multiclass classification
- Sigmoid and softmax functions

Data in machine learning

Types of data

- Numerical (quantitative): discrete / continuous
- Categorical (qualitative): nominal / ordinal
- Sequential / non-sequential

Examples

- Image data, video data, speech data
- Text data

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Data need to be collected and stored in a machine-readable form.

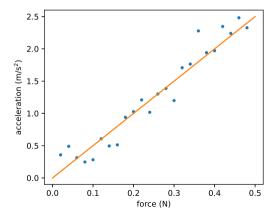


Image data



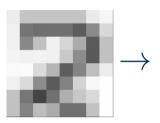
Image data



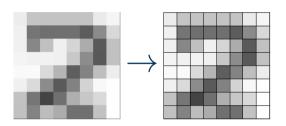
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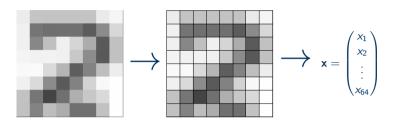
Pixel image to a feature vector



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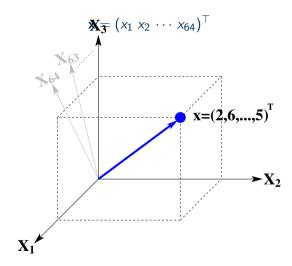


Turn each cell (pixel) into a number Unravel into a column vector, a *feature vector* \Rightarrow represented digit as point in 64*D*

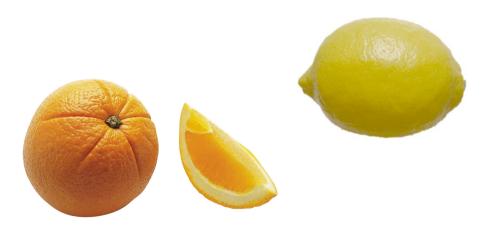
$$\mathbf{x} = (x_1 \ x_2 \ \cdots \ x_{64})^{\top}, \quad x_i \in [0, 127] \text{ or } x_i \in [0, 1]$$

http://alex.seewald.at/digits/

Image data as a point in a vector space

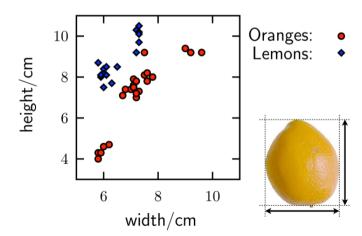


Classification of oranges and lemons



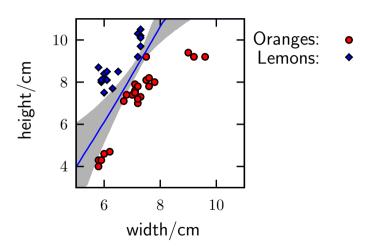
A two-dimensional space

Represent each sample as a point (w, h) in a 2D space



credit: Iain Murray

Classification



• Classes: $C = \{C_1, C_2, \dots, C_K\}$ Labels: $\mathcal{Y} = \{1, 2, \dots, K\}$

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$$p(C_k \mid \mathbf{x}) > p(C_{k'} \mid \mathbf{x}) \quad \forall k' \neq k \qquad p(y = k \mid \mathbf{x}) > p(y = k' \mid \mathbf{x}) \quad \forall k' \neq k$$

$$\hat{y}(\mathbf{x}) = \arg\max_{k} p(C_k \mid \mathbf{x})$$
(1)

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$$\hat{y}(\mathbf{x}) = \arg\max_{k} \, p(C_k \,|\, \mathbf{x}) \tag{1}$$

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$$\frac{posterior}{p(C_k \mid \mathbf{x})} = \frac{p(\mathbf{x} \mid C_k) p(C_k)}{p(\mathbf{x})} = \frac{p(\mathbf{x} \mid C_k) p(C_k)}{\sum_{k'=1}^{K} p(\mathbf{x} \mid C_{k'}) p(C_{k'})}$$

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Statistical classification (cont.)

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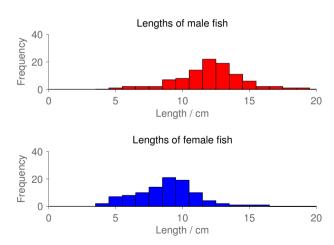
$$p(\mathbf{x} \mid C_k; \boldsymbol{\theta}), \ p(C_k; \boldsymbol{\theta})$$

• Discriminative classifier / approach : models LHS directly

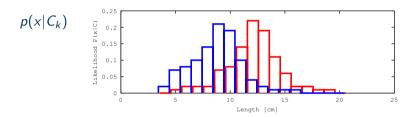
$$p(C_k \mid \boldsymbol{x}; \boldsymbol{\theta})$$

Example: determining the sex of fish

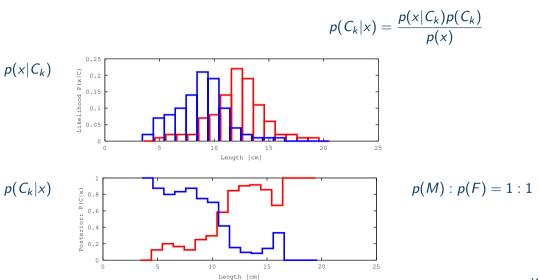
Histograms of fish lengths ($N_F = N_M = 100$)



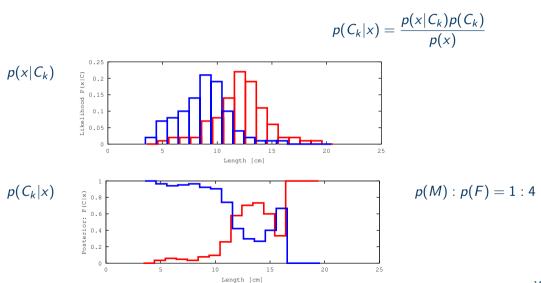
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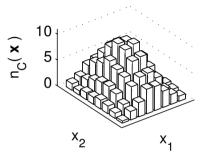
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1D histogram: $n_{C_k}(x_1)$

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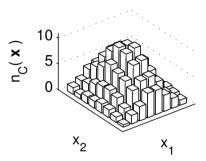


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3D cube of numbers: $n_{C_k}(x_1, x_2, x_3)$



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100 binary variables, 2^{100} settings (the universe is $\approx 2^{98}$ picoseconds old)

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⇒ Bellman's "curse of dimensionality"

Apply the chain rule?

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- ullet Assume $oldsymbol{x} \in \mathcal{R}^d$ distributes in a low dimensional vector space
 - Dimensionality reduction by PCA (Principal Component Analysis) / KL-transform

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• Is it reasonable?

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Is it reasonable?
 Often not, of course!
 Although it can still be useful.

Gaussian discriminant analysis

Consider a generative classifier where the class conditional densities are given as multivariate Gaussians:

$$p(\mathbf{x} \mid C_k; \boldsymbol{\theta}) = \mathcal{N}(\mathbf{x} \mid \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$
(3)

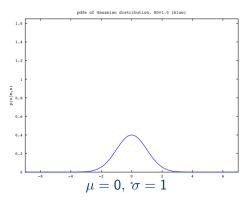
$$= \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}_k|^{1/2}} \exp\left(-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu}_k)^{\top} \boldsymbol{\Sigma}_k^{-1} (\boldsymbol{x} - \boldsymbol{\mu}_k)\right) \tag{4}$$

where μ_k is the mean vector and Σ_k is the covariance matrix for class C_k . The posterior:

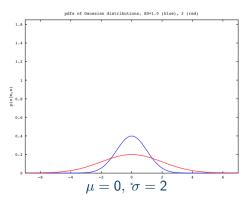
$$p(C_k | \mathbf{x}) \propto p(C_k) \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

This classifier is called Gaussian discriminant analysis or GDA.

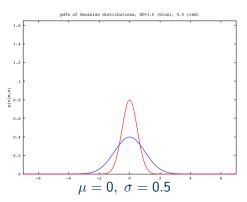
$$N(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(x-\mu)^2}{2\sigma^2}\right)$$



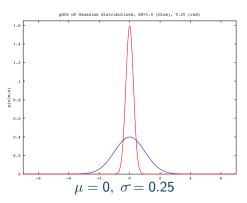
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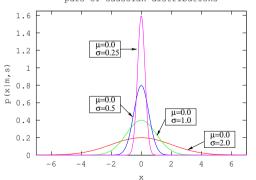
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pdfs of Gaussian distributions



$$\int_{-\infty}^{\infty} N(x; \mu, \sigma^2) dx = 1$$

$$\lim_{n \to \infty} N(x; \mu, \sigma^2) = \delta(x - \mu)$$

 $\lim_{\sigma \to 0} N(x; \mu, \sigma^2) = \delta(x - \mu)$

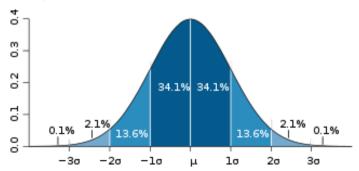
(Dirac delta function)

Facts about the Gaussian distribution

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- A Gaussian can be used to describe approximately any random variable that tends to cluster around the mean
- Concentration:
 - About 68% of values drawn from a normal distribution are within one SD away from the mean
 - About 95% are within two SDs.
 - About 99.7% lie within three SDs of the mean



The multidimensional Gaussian distribution

• The *d*-dimensional vector $\mathbf{x} = (x_1 \cdots x_d)^{\top}$ is multivariate Gaussian if it has a probability density function of the following form:

$$ho(\mathbf{x} \,|\, oldsymbol{\mu}, oldsymbol{\Sigma}) = rac{1}{(2\pi)^{d/2} |oldsymbol{\Sigma}|^{1/2}} \exp\left(-rac{1}{2}(\mathbf{x} - oldsymbol{\mu})^{ op} oldsymbol{\Sigma}^{-1}(\mathbf{x} - oldsymbol{\mu})
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- The 1-dimensional Gaussian is a special case of this pdf
- The argument to the exponential $\frac{1}{2}(\mathbf{x} \boldsymbol{\mu})^{\top} \Sigma^{-1}(\mathbf{x} \boldsymbol{\mu})$ is referred to as a quadratic form.

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- The sign of the covariance σ_{ij} helps to determine the relationship between two components:
 - If x_j is large when x_i is large, then $(x_j \mu_j)(x_i \mu_i)$ will tend to be positive;

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• The covariance matrix Σ is the expectation of the deviation of x from the mean:

$$\mathbf{\Sigma} = E[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^{\top}]$$

• Σ is a $d \times d$ symmetric matrix: $\Sigma^{\top} = \Sigma$

$$\sigma_{ij} = E[(x_i - \mu_i)(x_i - \mu_i)] = E[(x_i - \mu_i)(x_i - \mu_i)] = \sigma_{ii}$$
.

- The sign of the covariance σ_{ij} helps to determine the relationship between two components:
 - If x_i is large when x_i is large, then $(x_i \mu_i)(x_i \mu_i)$ will tend to be positive;
 - If x_j is small when x_i is large, then $(x_j \mu_j)(x_i \mu_i)$ will tend to be negative.

Covariance matrix

$$\Sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \cdots & \cdots & \sigma_{1d} \\ \sigma_{21} & \sigma_{22} & \cdots & \cdots & \sigma_{2d} \\ \vdots & \vdots & \ddots & & \vdots \\ \vdots & \vdots & & \sigma_{ii} & & \vdots \\ \vdots & \vdots & & & \ddots & \vdots \\ \sigma_{d1} & \sigma_{d2} & \cdots & \cdots & \sigma_{dd} \end{pmatrix}$$

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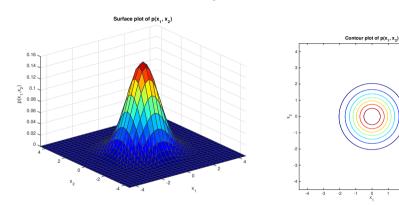
Covariance matrix

$$\Sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \cdots & \cdots & \sigma_{1d} \\ \sigma_{21} & \sigma_{22} & \cdots & \cdots & \sigma_{2d} \\ \vdots & \vdots & \ddots & & \vdots \\ \vdots & \vdots & & \sigma_{ii} & & \vdots \\ \vdots & \vdots & & & \ddots & \vdots \\ \sigma_{d1} & \sigma_{d2} & \cdots & \cdots & \sigma_{dd} \end{pmatrix}$$

- $\sigma_i^2 = \sigma_{ii}$
- $|\Sigma| = \det(\Sigma)$: determinant

e.g. for
$$d=2$$
, $|\Sigma|=\left|\begin{array}{cc} a & b \\ c & d \end{array}\right|=a\times d-b\times c$

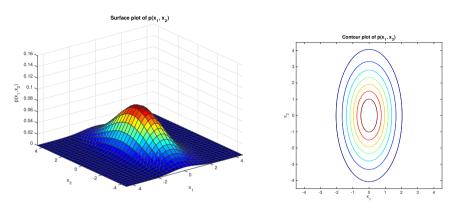
Spherical Gaussian



$$oldsymbol{\mu} = \left(egin{array}{c} 0 \ 0 \end{array}
ight) \qquad oldsymbol{\Sigma} = \left(egin{array}{c} 1 & 0 \ 0 & 1 \end{array}
ight) \qquad
ho_{12} = 0$$

NB: Correlation coefficient
$$\rho_{ij} = \frac{\sigma_{ij}}{\sqrt{\sigma_{ii}\sigma_{ii}}}$$
 $(-1 \le \rho_{ij} \le 1)$ _{24/41}

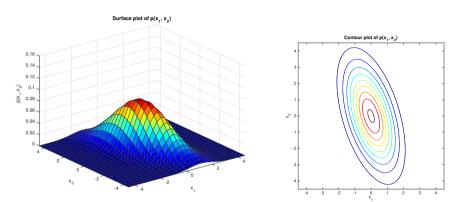
2-D Gaussian with a diagonal covariance matrix



$$oldsymbol{\mu} = \left(egin{array}{c} 0 \ 0 \end{array}
ight) \qquad oldsymbol{\Sigma} = \left(egin{array}{c} 1 & 0 \ 0 & 4 \end{array}
ight) \qquad
ho_{12} = 0$$

NB: Correlation coefficient
$$\rho_{ij} = \frac{\sigma_{ij}}{\sqrt{\sigma_{ii}\sigma_{ii}}}$$
 $(-1 \le \rho_{ij} \le 1)$ _{25/41}

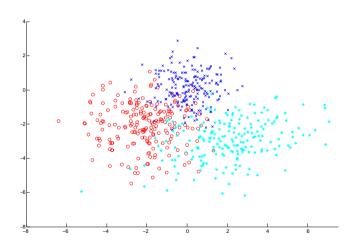
2-D Gaussian with a full covariance matrix



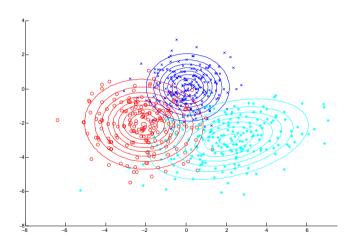
$$\mu = \left(egin{array}{c} 0 \ 0 \end{array}
ight) \qquad oldsymbol{\Sigma} = \left(egin{array}{cc} 1 & -1 \ -1 & 4 \end{array}
ight) \qquad
ho_{12} = -0.5$$

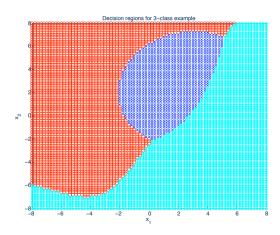
NB: Correlation coefficient $\rho_{ij} = \frac{\sigma_{ij}}{\sqrt{\sigma_{ii}\sigma_{ii}}}$ $(-1 \le \rho_{ij} \le 1)$ _{26/41}

Gaussians estimated from data



Gaussians estimated from data





• Recall Bayes' Rule:

$$p(C_k|\mathbf{x}) = \frac{p(\mathbf{x}|C_k)p(C_k)}{p(\mathbf{x})}$$

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$$(k^* = \arg\max_k p(C_k|x))$$

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Decision regions

• Recall Bayes' Rule:

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- Given an unseen point x, we assign to the class for which $p(C_k|x)$ is largest. $(k^* = \arg \max_k p(C_k|x))$
- Thus **x**-space (the input space) may be regarded as being divided into decision regions \mathcal{R}_k such that a point falling in \mathcal{R}_k is assigned to class C_k .
- Decision region \mathcal{R}_k need not be contiguous, but may consist of several disjoint regions each associated with class C_k .
- The boundaries between these regions are called *decision boundaries*.

Placement of decision boundaries

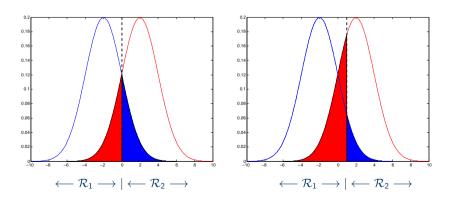
• Consider a 1-dimensional feature space (x) and two classes C_1 and C_2 .

Placement of decision boundaries

- Consider a 1-dimensional feature space (x) and two classes C_1 and C_2 .
- How to place the decision boundary to minimise the probability of misclassification (based on $p(x, C_k)$)?

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Confusion matrix

$In \setminus Out$	C_1	C_2
C_1	N_{11}	N_{12}
C_2	N_{21}	N_{22}

$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	C_1	C_2
C_1	P_{11}	P_{12}
C_2	P_{21}	P_{22}

$$P_{11} + P_{12} = 1$$

$$P_{21} + P_{22} = 1$$

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$$P_{11} + P_{12} = 1$$
$$P_{21} + P_{22} = 1$$

$$\begin{aligned} P_{11} &= p(x \in \mathcal{R}_1 | C_1) = \frac{N_{11}}{N_1}, & P_{12} &= p(x \in \mathcal{R}_2 | C_1) = \frac{N_{12}}{N_1} \\ P_{21} &= p(x \in \mathcal{R}_1 | C_2) = \frac{N_{21}}{N_2}, & P_{22} &= p(x \in \mathcal{R}_2 | C_2) = \frac{N_{22}}{N_2} & \text{g da} + \\ N_1 &= N_{11} + N_{12}, & N_2 &= N_{21} + N_{22}, & p(C_1) = \frac{N_1}{N_1 + N_2}, & p(C_2) = \frac{N_2}{N_2 + N_2} \end{aligned}$$

Confusion matrix

$$P_{11} + P_{12} = 1$$
$$P_{21} + P_{22} = 1$$

$$\begin{split} P_{11} &= p(x \in \mathcal{R}_1 | C_1) = \frac{N_{11}}{N_1}, \quad P_{12} = p(x \in \mathcal{R}_2 | C_1) = \frac{N_{12}}{N_1} \\ P_{21} &= p(x \in \mathcal{R}_1 | C_2) = \frac{N_{21}}{N_2}, \quad P_{22} = p(x \in \mathcal{R}_2 | C_2) = \frac{N_{22}}{N_2} \quad \text{g da} + \\ N_1 &= N_{11} + N_{12}, \ N_2 = N_{21} + N_{22}, \ p(C_1) = \frac{N_1}{N_1 + N_2}, \ p(C_2) = \frac{N_2}{N_1 + N_2} \\ p(\text{correct}) &= \frac{N_{11} + N_{22}}{N_1 + N_2} = P_{11} \ p(C_1) + P_{22} \ p(C_2) \end{split}$$

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Confusion matrix

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Mormalised version

Comusion matrix	Normalised Version	
In\Out C_1 C_2		
C_1 N_{11} N_{12}	$\Rightarrow \begin{array}{c cccc} \hline \text{In}\backslash \text{Out} & C_1 & C_2 \\ \hline C_1 & P_{11} & P_{12} \\ C_2 & P_{21} & P_{22} \\ \end{array} \begin{array}{c ccccc} P_{11} + P_{12} = 1 \\ P_{21} + P_{22} = 1 \\ \end{array}$	
$C_2 N_{21} N_{22}$	$C_2 P_{21} P_{22} $ $P_{21} + P_{22} = 1$	
$P_{11} = p(x \in \mathcal{R})$ $P_{21} = p(x \in \mathcal{R})$	$egin{align} egin{align} eg$	
$p(\text{correct}) = \frac{N_{11} + N_{11}}{N_1 + N_{11}}$	$N_1 = N_{11} + N_{12}, \ N_2 = N_{21} + N_{22}, \ p(C_1) = \frac{N_1}{N_1 + N_2}, \ p(C_2) = \frac{N_2}{N_1}$ $\frac{N_2}{N_2} = P_{11} p(C_1) + P_{22} p(C_2)$	$\frac{V_2}{+N_2}$
$p(\text{error}) = \frac{N_{12} + N_{12}}{N_1 + N_2}$	$\frac{J_{21}}{J_2} = P_{12} p(C_1) + P_{21} p(C_2)$	

 $= \int_{\mathcal{R}_2} p(x|C_1) \, p(C_1) \, dx + \int_{\mathcal{R}_2} p(x|C_2) \, p(C_2) \, dx$

 $= \int_{\mathcal{P}} p(C_1|x) p(x) dx + \int_{\mathcal{P}} p(C_2|x) p(x) dx$

Confusion matrix

$$p(\operatorname{error}|\mathcal{R}_1, \mathcal{R}_2) = \int_{\mathcal{R}_2} p(C_1|x) \, p(x) \, dx + \int_{\mathcal{R}_1} p(C_2|x) \, p(x) \, dx \tag{5}$$

$$p(\operatorname{error}|\mathcal{R}_1, \mathcal{R}_2) = \int_{\mathcal{R}_2} p(C_1|x) \, p(x) \, \mathrm{d}x + \int_{\mathcal{R}_1} p(C_2|x) \, p(x) \, \mathrm{d}x \tag{5}$$

• If $\hat{x} = x_0 \in \mathcal{R}_2$ such that $p(C_1 | x_0) > p(C_2 | x_0)$,

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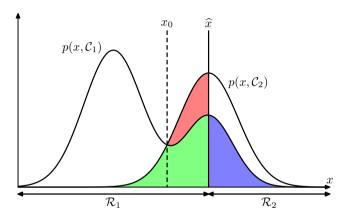
 p(error) is minimised by assigning each point to the class with the maximum posterior probability – Bayes decision rule / MAP decision rule / minimum error rate classification.

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- p(error) is minimised by assigning each point to the class with the maximum posterior probability Bayes decision rule / MAP decision rule / minimum error rate classification.
- This justification for the maximum posterior probability may be extended to d-dimensional feature vectors and K classes



After Fig. 1.24, C. Bishop, Pattern Recognition and Machine Learning, Springer, 2006.

 \hat{x} denotes the current decision boundary, which causes error shown in red, green, and blue regions. The error is minimised by locating the boundary at x_o .

Should we always use the Bayes decision rule?

See "Predictions and Decision Boundaries", LWLS 3.2.

Recall GDA

$$p(C_k | \mathbf{x}, \mathbf{\theta}) \propto p(C_k) \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

where

$$\mathcal{N}(\boldsymbol{x} \mid \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}_k|^{1/2}} \exp\left(-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu}_k)^{\top} \boldsymbol{\Sigma}_k^{-1} (\boldsymbol{x} - \boldsymbol{\mu}_k)\right)$$
(6)

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• The discriminant function of GDA: (taking log and ignoring constant terms yields)

$$g_k(\mathbf{x}) = \log p(C_k) - \frac{1}{2} \log |\mathbf{\Sigma}_k| - \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^{\top} \mathbf{\Sigma}_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k)$$
(7)

 \cdots quadratic function of x.

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Classification (estimating the class label):

$$\hat{y}(\mathbf{x}) = \arg\max_{k} g_k(\mathbf{x}) \tag{8}$$

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Classification (estimating the class label):

$$\hat{y}(\mathbf{x}) = \arg\max_{k} g_k(\mathbf{x}) \tag{8}$$

• So, the decision boundaries are quadratic functions of x. (Check!)

Assume all class cavariances Σ_k share the same covariance, $\Sigma_k = \Sigma$. The discriminant function is reduced to

$$g_k(\mathbf{x}) = \log p(C_k) - \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^{\top} \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}_k)$$
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$$= \log p(C_k) + \boldsymbol{\mu}_k^{\top} \boldsymbol{\Sigma}^{-1} \mathbf{x} - \frac{1}{2} \boldsymbol{\mu}_k^{\top} \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_k - \frac{1}{2} \mathbf{x}^{\top} \boldsymbol{\Sigma}^{-1} \mathbf{x}$$
(10)

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 (10)

$$= \boldsymbol{w}_k^{\top} \boldsymbol{x} + w_{k0} + \text{const} \tag{11}$$

where
$$\mathbf{w}_k^{\top} = \mathbf{\mu}_k^{\top} \mathbf{\Sigma}^{-1} \ w_{k0} = -\frac{1}{2} \mathbf{\mu}_k^{\top} \mathbf{\Sigma}^{-1} \mathbf{\mu}_k + \log p(C_k)$$

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where
$$\mathbf{w}_k^{\top} = \mu_k^{\top} \mathbf{\Sigma}^{-1} \ w_{k0} = -\frac{1}{2} \mu_k^{\top} \mathbf{\Sigma}^{-1} \mu_k + \log p(C_k)$$

This is called a *linear discriminant function* as it is a linear function of x. The method is called *Linear Discriminant Analysys (LDA)*.

Including the constant terms to w_{k0} , we have:

$$g_k(\mathbf{x}) = \mathbf{w}_k^{\top} \mathbf{x} + w_{k0} \tag{12}$$

Since $g_k(\mathbf{x}) = \log p(C_k) p(\mathbf{x} \mid C_k, \boldsymbol{\theta})$,

$$p(C_k \mid \mathbf{x}, \boldsymbol{\theta}) = \frac{g_k(\mathbf{x})}{\sum_{k'=1}^K g_{k'}(\mathbf{x})}$$
(13)

$$= \frac{e^{\mathbf{w}_{k}^{\top} \mathbf{x} + w_{k0}}}{\sum_{k'=1}^{K} e^{\mathbf{w}_{k'}^{\top} \mathbf{x} + w_{k'0}}}$$
(14)

• Spherical Gaussians:
$$\Sigma = \sigma^2 \mathbf{I} \quad \Rightarrow \quad |\Sigma| = \sigma^{2d}, \quad \Sigma^{-1} = \frac{1}{\sigma^2} \mathbf{I}$$

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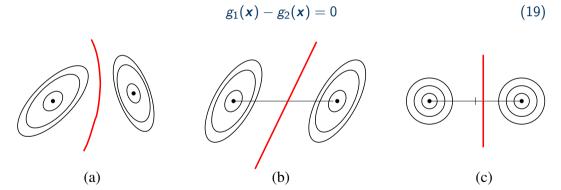
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The class means (μ_k) may be regarded as class templates or prototypes.

Decision boundaries of GDA

Consider a binary classification between C_1 and C_2 .



Quizzes

Show:

$$p(C_k \mid \mathbf{x}) = \frac{p(\mathbf{x} \mid C_k) p(C_k)}{\sum_{k'=1}^{K} p(\mathbf{x} \mid C_{k'}) p(C_{k'})}$$

- Write Python code that generates 2D and 3D visualisations of a two-dimensional Gaussian distribution with a specified mean vector and covariance matrix.
 - Run the code using various sets of parameters.
 - You will find that the code does not work with some covariance matrices. Describe the conditions for valid covariance matrices.

Quizzes (cont.)

• Show that the natural logarithm of a multivariate Gaussian distribution

$$\mathcal{N}(oldsymbol{x} \,|\, oldsymbol{\mu}, oldsymbol{\Sigma}) = rac{1}{(2\pi)^{d/2} |oldsymbol{\Sigma}|^{1/2}} \exp\left(-rac{1}{2} (oldsymbol{x} - oldsymbol{\mu})^ op oldsymbol{\Sigma}^{-1} (oldsymbol{x} - oldsymbol{\mu})
ight)$$

is given as

$$-\frac{1}{2}\mathbf{x}^{\top}\boldsymbol{\Sigma}^{-1}\mathbf{x} + \boldsymbol{\mu}\boldsymbol{\Sigma}^{-1}\mathbf{x} - \frac{1}{2}\boldsymbol{\mu}^{\top}\boldsymbol{\Sigma}^{-1}\boldsymbol{\mu} - \frac{1}{2}\log|\boldsymbol{\Sigma}| - \frac{d}{2}\log 2\pi$$