### Sheaf representation of monoidal categories

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# Categories should be nice and easy

Category **Vect** of vector spaces is monoidal. So is **Vect** × **Vect**. Clearly **Vect** is **easier**: does not decompose as product.

Any monoidal category embeds into a nice one, and any nice monoidal category is dependent product of easy ones.

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Category is easy if subunits are like singletons:

(sub)local: any (finite) cover contains the open that is covered every net converges to a single focal point

# Sheaves are continuously parametrised objects

Write  $\mathcal{O}(X)$  for open sets of space X.

Presheaf on X is functor  $F \colon \mathcal{O}(X)^{\mathrm{op}} \to \mathbf{Set}$ Elements of F(U) are called *local sections*. Elements of F(X) are called *global sections*. Map  $F(U \subseteq V) \colon F(V) \to F(U)$  is called *restriction*.

### Sheaf condition

Sheaf is continuous presheaf:  $F(\text{colim } U_i) = \lim F(U_i)$ 

- ▶ Elements of F(U) are *global sections* over  $U = \text{colim } U_i = \bigcup U_i$
- $\blacktriangleright$  Elements of  $\lim F(U_i)$  are compatible local sections:

$$\lim F(U_i) = \big\{ (s_i) \mid F(U_i \cap U_j \subseteq U_i)(s_i) = F(U_i \cap U_j \subseteq U_j)(s_j) \big\}$$

Compatible local sections must glue together to unique global section

Example:  $F(U) = \{ \text{ continuous functions } U \to \mathbb{R} \}$ 

### Sheaves of categories

What if F takes values not in **Set** but in **V**?

Then sheaf condition becomes equaliser in **V**:

$$F(\bigcup_{i}U_{i}) \xrightarrow{\langle F(U_{i}\subseteq \cup U_{i})\rangle_{i}} \prod_{i}F(U_{i}) \xrightarrow{\langle F(U_{i}\cap U_{j}\subseteq U_{i})\circ\pi_{i}\rangle_{i,j}} \prod_{i,j}F(U_{i}\cap U_{j})$$

### Stalk

of sheaf F at point x is  $colim\{F(U) \mid x \in U\}$ 

Say F is a "sheaf of ..." when its stalks are "..." E.g. sheaves of local rings

# Sheaf representation

#### Literature:

- ▶ Boolean algebra is global sections of sheaf of spaces {0,1}
- ring is ring of global sections of sheaf of local rings
- ▶ topos is category of global sections of sheaf of local toposes

#### Will generalise all three into:

 monoidal category with universal join of subunits is category of global sections of sheaf of local monoidal categories

#### Corollary:

 stiff monoidal category embeds into category of global sections of sheaf of local monoidal categories

#### **Subunits**

How to recover  $\mathcal{O}(X)$  from  $\mathrm{Sh}(X)$ ? Look at subobjects of terminal object  $s \colon S \rightarrowtail 1$ .

What if we want sheaves with values not in **Set**? A subunit in a monoidal category **C** is a subobject  $s: S \rightarrow I$  such that  $S \otimes s: S \otimes S \rightarrow S \otimes I$  is invertible. They form set  $ISub(\mathbf{C})$ .

- ▶  $\mathsf{ISub}(\mathsf{Sh}(X)) = \mathcal{O}(X)$
- ▶  $\mathsf{ISub}(L) = L$  for semilattice L
- ▶  $\mathsf{ISub}(\mathbf{Mod}_R) = \{I \subseteq R \text{ ideal } | I^2 = I\}$  for commutative ring R
- ▶  $\mathsf{ISub}(\mathbf{Hilb}_{C(X)}) = \mathcal{O}(X)$

#### Nice subunits

Draw subunit as 
$$\bigcirc_s$$
, and draw  $\bigcirc_s^s$  for inverse of  $\bigcirc_s$   $\Big|_s = \Big|_s^\circ \bigcirc_s$ 

#### Nicer subunits

$$s \leq t$$
 if there is unique  $m: S \rightarrow T$  with  $s = t \circ m$ :

$$\bigcap_{S} = \bigcap_{S}$$

ISub(C) distributive lattice

- C has universal finite joins of subunits
- $\iff$  ISub(**C**) has finite joins,  $0 \simeq 0 \otimes A$  is initial, and

# **Embedding**

Stiff **C** embeds into category with universal finite joins of subunits embeds into category with universal joins of subunits

Universally, faithfully, preserving subunits and tensor products

### Base space

C has universal (finite) joins of subunits

 $\implies$  ISub(**C**) is a (distributive lattice) frame

 $\implies$  Zariski spectrum  $X = \text{Spec}(ISub(\mathbf{C}))$  is topological space

points x are (completely) prime filters in ISub(C)

# Local sections F(s)

- ▶ Objects: as in **C**
- ▶ Morphisms:  $A \otimes S \rightarrow B$  in **C**
- Composition:
- ► Identity:
- Tensor product: f g

#### Sheaf condition

To specify a sheaf  $F \colon \mathcal{O}(X)^{\operatorname{op}} \to \operatorname{MonCat}$ , it's enough to give a presheaf  $F \colon \operatorname{ISub}(\mathbf{C})^{\operatorname{op}} \to \operatorname{MonCat}$ , such that F(0) is terminal and the following is an equaliser:

$$F(s \lor t) \xrightarrow{\langle F(s \le s \lor t), F(t \le s \lor t) \rangle} F(s) \times F(t) \xrightarrow{F(s \land t \le s) \circ \pi_1} F(s \land t)$$

# Stalks F(x) are (sub)local

- Objects: as in **C**
- ▶ Morphisms:  $A \otimes S \rightarrow B$  in **C** for  $s \in x$ , identified when

► Composition of (s, f) and (t, g) is



#### **Theorem**

Any small stiff category with universal (finite) joins of subunits is monoidally equivalent to category of global sections of sheaf of (sub)local categories.

Any small stiff category embeds into a category of global sections of a sheaf of local categories.

### Preservation

category	local sections	stalks
stiff	monoidal	stiff
closed	closed	closed
traced	traced	traced
compact	compact	compact
Boolean		two-valued
limits	limits	limits
projective colimits	colimits	colimits

#### Conclusion

- Cleanly separate 'spatial' from 'temporal' directions
- Does for multiplicative linear logic what was known for intuitionistic logic
- Directly capture more examples
- Concrete proof

- Completeness theorem?
- Coherence theorem?
- Restriction categories?
- Applications in computer science? Probability? Quantum theory?

#### References

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### Restriction categories

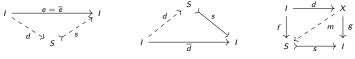
Turn monoidal category  $\mathbf{C}$  into restriction category  $S[\mathbf{C}]$ :

- ▶ Objects: as in C
- ▶ Morphisms:  $A \otimes S \rightarrow B$  in **C**
- ▶ Identity:  $A \otimes I \rightarrow A$
- Tensor product: f g
- $\blacktriangleright \text{ Restriction: } \left( \left| \frac{|B|}{f} \right|_{A} \right|_{S} \right) = \left| \bigcirc_{A} \right|_{S}$

# Tensor-restriction categories

point is  $d: I \rightarrow S$  with restriction inverse that is tensor-total







- ▶ any  $e = \overline{e}: I \rightarrow I$  factors via subunit s and point d
- any subunit s has point as restriction section
- ▶ any  $f = \overline{f}: X \to X$  equals  $f = e \bullet X$  for unique  $e = \overline{e}: I \to I$
- ▶ any tensor-total f equals  $f = g \circ \overline{f}$  for a unique restriction-total g;
- points left-lift against subunits
- points are closed under tensor product
- points are determined by codomain up to unique scalar