## Sheaf representation of monoidal categories

Chris Heunen



## Categories should be nice and easy

Category **Vect** of vector spaces is monoidal. So is **Vect** × **Vect**. Clearly **Vect** is **easier**: does not decompose as product.

Any monoidal category embeds into a nice one, and any nice monoidal category is dependent product of easy ones.

## Nice and easy

 $\prod_{i \in \{0,1\}} \textbf{Vect}$  is decomposable since  $\{0,1\}$  is disjoint union

Can reconstruct opens of  $\{0,1\}$  as subunits of  $\textbf{Vect} \times \textbf{Vect}$ 

## Nice and easy

 $\prod_{i \in \{0,1\}}$  **Vect** is decomposable since  $\{0,1\}$  is disjoint union

Can reconstruct opens of  $\{0,1\}$  as *subunits* of **Vect**  $\times$  **Vect** 

Category is nice if subunits form frame respected by tensor product:

- stiff: subunits form semilattice
- universal joins of subunits: subunits form complete lattice

## Nice and easy

 $\prod_{i \in \{0,1\}}$  **Vect** is decomposable since  $\{0,1\}$  is disjoint union

Can reconstruct opens of  $\{0,1\}$  as *subunits* of **Vect**  $\times$  **Vect** 

Category is nice if subunits form frame respected by tensor product:

- stiff: subunits form semilattice
- universal joins of subunits: subunits form complete lattice

Category is easy if subunits are like singletons:

(sub)local: any (finite) cover contains the open that is covered every net converges to a single focal point

## Sheaves are continuously parametrised objects

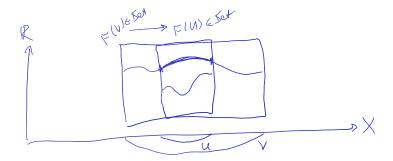
Write  $\mathcal{O}(X)$  for open sets of space X.

Presheaf on X is functor  $F: \mathcal{O}(X)^{\mathrm{op}} \to \mathbf{Set}$ 

Elements of F(U) are called *local sections*.

Elements of F(X) are called *global sections*.

Map  $F(U \subseteq V)$ :  $F(V) \rightarrow F(U)$  is called *restriction*.



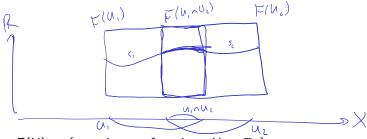
#### Sheaf condition

Sheaf is continuous presheaf:  $F(\text{colim } U_i) = \lim F(U_i)$ 

- ▶ Elements of F(U) are *global sections* over  $U = \text{colim } U_i = \bigcup U_i$
- $\blacktriangleright$  Elements of  $\lim F(U_i)$  are compatible local sections:

$$\lim F(U_i) = \big\{ (s_i) \mid F(U_i \cap U_j \subseteq U_i)(s_i) = F(U_i \cap U_j \subseteq U_j)(s_j) \big\}$$

Compatible local sections must glue together to unique global section



Example:  $F(U) = \{ \text{ continuous functions } U \to \mathbb{R} \}$ 

## Sheaves of categories

What if *F* takes values not in **Set** but in **V**?

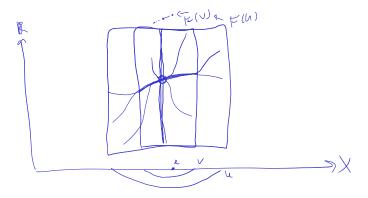
Then sheaf condition becomes equaliser in **V**:

$$F(\bigcup_{i} U_{i}) \xrightarrow{\langle F(U_{i} \subseteq \bigcup U_{i}) \rangle_{i}} \prod_{i} F(U_{i}) \xrightarrow{\langle F(U_{i} \cap U_{j} \subseteq U_{i}) \circ \pi_{i} \rangle_{i,j}} \prod_{i,j} F(U_{i} \cap U_{j})$$

$$\downarrow f_{i} \downarrow f_{i}$$

### Stalk

of sheaf F at point x is  $\operatorname{colim}\{F(U) \mid x \in U\}$ 



Say F is a "sheaf of ..." when its stalks are "..." E.g. sheaves of local rings

## Sheaf representation

#### Literature:

- ▶ Boolean algebra is global sections of sheaf of spaces {0,1}
- ring is ring of global sections of sheaf of local rings
- topos is category of global sections of sheaf of local toposes
- or restriction monorids?

#### Will generalise all three into:

 monoidal category with universal join of subunits is category of global sections of sheaf of local monoidal categories

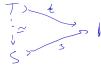


#### Corollary:

 stiff monoidal category embeds into category of global sections of sheaf of local monoidal categories

#### Subunits

How to recover  $\mathcal{O}(X)$  from Sh(X)? Look at subobjects of terminal object  $s: S \rightarrow 1$ .



What if we want sheaves with values not in **Set**?

A subunit in a monoidal category **C** is a subobject  $s: S \rightarrow I$ such that  $S \otimes s : S \otimes S \to S \otimes I$  is invertible. They form set  $ISub(\mathbf{C})$ .

- |Sub(L)| = U(X)| Sub(Mode) (X)▶  $\mathsf{ISub}(\mathbf{Mod}_R) = \{I \subseteq R \text{ ideal } | I^2 = I\}$  for commutative ring R
- ► ISub(**Hilb**<sub>C(X)</sub>) = O(X)

#### Nice subunits

Draw subunit as 
$$\cite{S}$$
, and draw  $\cite{S}$  for inverse of  $\cite{S}$   $\cite{S}$   $\cite{S}$   $\cite{S}$ 

$$|\mathsf{Sub}(\mathbf{C}) \text{ semilattice} \iff \mathbf{C} \text{ is stiff} \iff \\ S \otimes T \otimes A \longmapsto T \otimes A \\ \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \\ S \otimes A \longmapsto A \qquad \qquad \bigcirc_{S} \ \bigcirc_{T} \ \Big|_{A} = \bigcirc_{S} \ \bigcirc_{T} \ \Big|_{A}$$

#### Nicer subunits

s < t if there is unique  $m: S \to T$  with  $s = t \circ m$ :



ISub(C) distributive lattice

- C has universal finite joins of subunits
- $\iff$  ISub(**C**) has finite joins,  $0 \simeq 0 \otimes A$  is initial, and

## **Embedding**

Stiff **C** embeds into category with universal finite joins of subunits embeds into category with universal joins of subunits

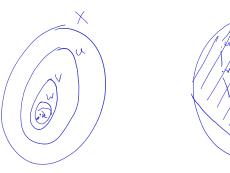
Universally, faithfully, preserving subunits and tensor products

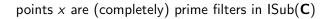
## Base space

C has universal (finite) joins of subunits

 $\implies$  ISub( $\mathbf{C}$ ) is a (distributive lattice) frame

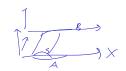
 $\implies$  Zariski spectrum  $X = \text{Spec}(\mathsf{ISub}(\mathbf{C}))$  is topological space





# Local sections F(s) = ke(s )

- ▶ Objects: as in **C**
- ▶ Morphisms:  $A \otimes S \rightarrow B$  in **C**



► Composition:



► Tensor product:



$$T_{s}GC \xrightarrow{\longrightarrow} F(s)$$

$$T_{s}JSwb(C) \xrightarrow{\longrightarrow} [C,C]$$

#### Sheaf condition

To specify a sheaf  $F \colon \mathcal{O}(X)^{\operatorname{op}} \to \operatorname{MonCat}$ , it's enough to give a presheaf  $F \colon \operatorname{ISub}(\mathbf{C})^{\operatorname{op}} \to \operatorname{MonCat}$ , such that F(0) is terminal and the following is an equaliser:

$$F(s \lor t) \xrightarrow{\langle F(s \le s \lor t), F(t \le s \lor t) \rangle} F(s) \times F(t) \xrightarrow{F(s \land t \le s) \circ \pi_1} F(s \land t)$$

$$F(s \lor t) \xrightarrow{F(s \land t \le t) \circ \pi_2} F(s \land t)$$

## Stalks F(x) are (sub)local

- ► Objects: as in **C**Morphisms:  $A \otimes S \xrightarrow{f} B$  in **C** for  $s \in x$ , identified when

$$\frac{f}{f} = \frac{f'}{|s'|} \quad \text{for some real Solic}$$

► Composition of (s, f) and (t, g) is



#### **Theorem**

Any small stiff category with universal (finite) joins of subunits is monoidally equivalent to category of global sections of sheaf of (sub)local categories.

Any small stiff category embeds into a category of global sections of a sheaf of local categories.

## Preservation

eservation		of Catu	nim
	$\mathcal{C}$	F(s) = C/s	F(x)
	category	local sections	stalks
	stiff	monoidal	stiff
	closed	closed	closed
	traced	traced	traced
,	compact	compact	compact $+ (\downarrow (\not x))$
po ((())	Boolean		two-valued (F(r))
مرطه	limits	limits	limits
,	projective colimits	colimits	colimits

#### Conclusion

- ► Cleanly separate 'spatial' from 'temporal' directions
- ns TETAL

- Does for multiplicative linear logic what was known for intuitionistic logic
- Directly capture more examples
- Concrete proof

- Completeness theorem?
- Coherence theorem?
- Restriction categories?
- ▶ Applications in computer science? Probability? Quantum theory?

#### References

"Space in monoidal categories" [arXiv:1704.08086]
 P. Enrique Moliner, C. Heunen, S.Tull

"Tensor topology" [arXiv:1810.01383]
 P. Enrique Moliner, C. Heunen, S. Tull

"Sheaf representation for monoidal categories" [arXiv:soon]
 R. Soares Barbosa, C. Heunen

► "Tensor-restriction categories" [arXiv:2009.12432]

C. Heunen, J. S. Pacaud Lemay

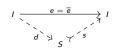
## Restriction categories

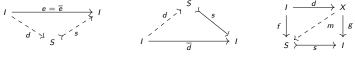
Turn restriction category  ${\bf C}$  into monoidal category  $S[{\bf C}]$ :

- ► Objects: as in C
- ▶ Morphisms:  $A \otimes S \rightarrow B$  in **C**
- ▶ Identity:  $A \otimes I \rightarrow A$
- Tensor product: f g
- $\blacktriangleright \text{ Restriction: } \left( \left| \frac{|B|}{f} \right|_{A} \right|_{S} \right) = \left| \bigcirc_{A} \right|_{S}$

## Tensor-restriction categories

point is  $d: I \rightarrow S$  with restriction inverse that is tensor-total







- ▶ any  $e = \overline{e}: I \rightarrow I$  factors via subunit s and point d
- any subunit s has point as restriction section
- ▶ any  $f = \overline{f}: X \to X$  equals  $f = e \bullet X$  for unique  $e = \overline{e}: I \to I$
- ▶ any tensor-total f equals  $f = g \circ \overline{f}$  for a unique restriction-total g;
- points left-lift against subunits
- points are closed under tensor product
- points are determined by codomain up to unique scalar